St**i**tGis Team

2nd StatGIS conference

Vector vs. Raster in Network Analysis







MINISTRY OF EDUCATION, YOUTH AND SPORTS



INVESTMENTS IN EDUCATION DEVELOPMENT

Vít Voženílek

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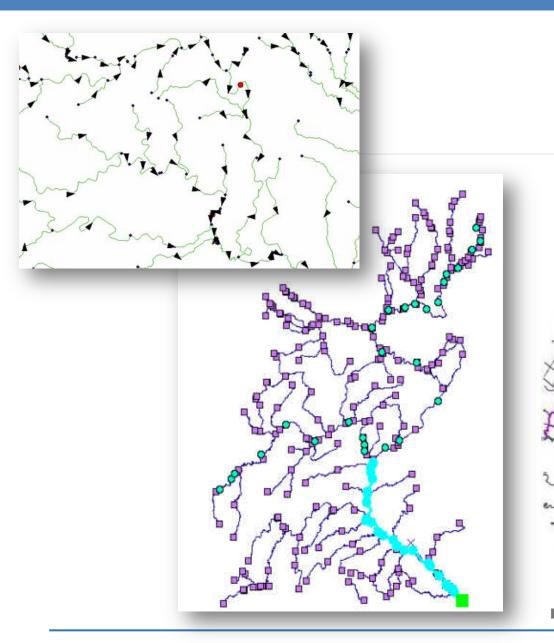


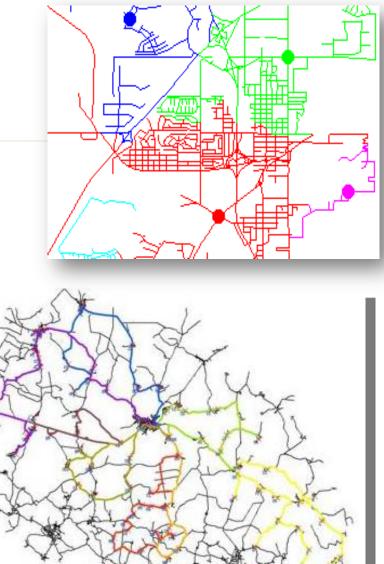




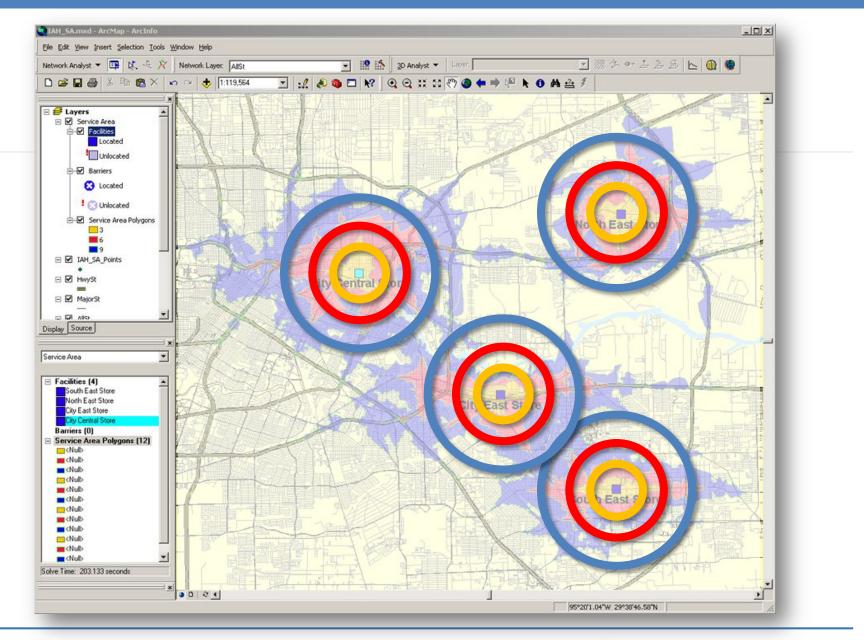














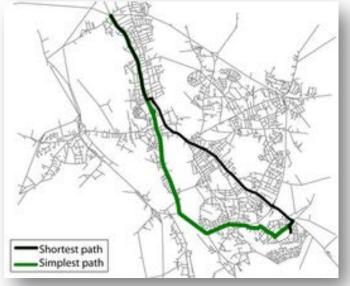
Network Analysis

- for solving routing and logistical problems on a network of connected lines in a vector object
 - to determine the optimal route connecting stops
 - to allocate different parts of the network to service areas around individual facility locations
- it utilizes the topology of the network and properties of the lines and intersections (such as one-way directions and impedance and demand values)
 - city streets, state highways, water or sewer pipelines, or some other utility network



Optimized Route

- to find the quickest, shortest, cheapest, most scenic route ...
- cost values: time, distance, time, slope, impression etc.
- just two stop locations or many stops in the best order

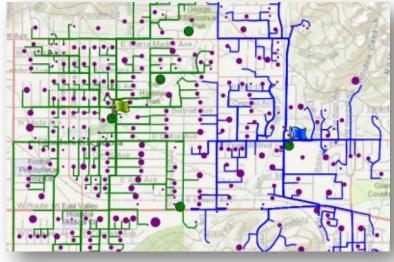






Closest Facilities

- to measure the cost of traveling between incidents and facilities to determine which are nearest to one other
- to specify how many to find, whether the direction of travel is toward or away, and other constraints like search cutoff thresholds





Multi-Vehicle Routing Problem

- to determine what stops should be serviced by each route and in what sequence the stops should be visited
 - given a set of work locations and a fleet of vehicles
- the solution minimizes the overall operating cost for the entire fleet while considering business rules you define

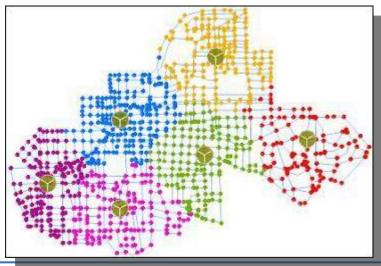




Location Allocation

- a right location keeps costs low and accessibility high, for maximizing profit and high-quality service
- the analysis takes into account facilities that provide goods and services, and where those good and services are

consumed

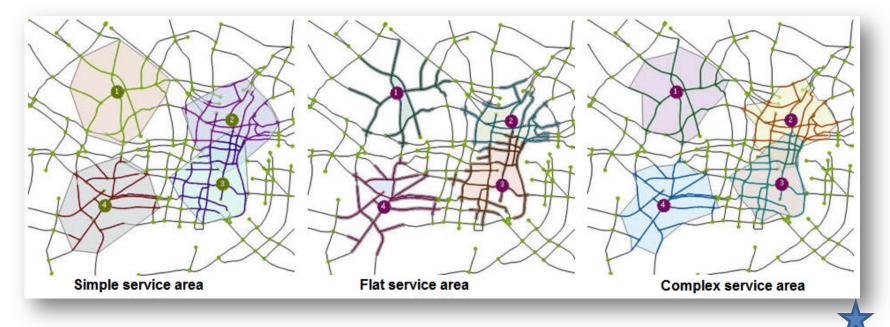






Service Area

• a network service area is a region that can be reached from a location within a given travel time or travel distance

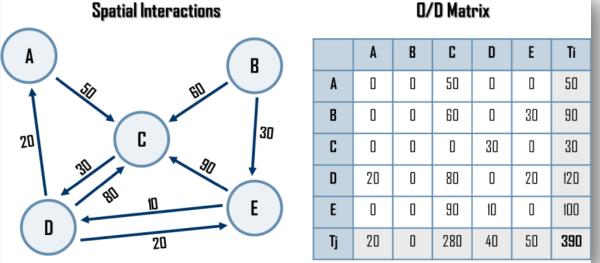






Origin–Destination (O-D) Cost Matrix

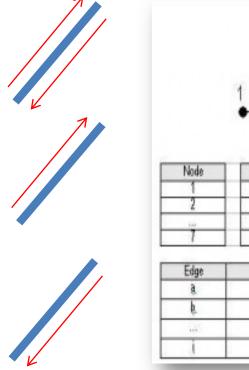
- the O-D cost matrix produces a distance table, with least-cost paths along the network from many origins to many destinations
- the cost values reflect the network distance, not the straight-line distance
 Snatial Interactions

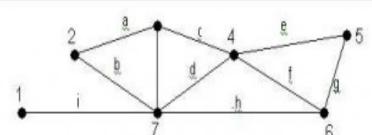




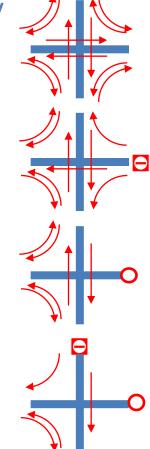


Arcs and nodes [stops, centres, turns, barriers] + topology





Node	Edge	From	To	Node	From	To	Impedance	
1	a	2	3	1	i	d	1	
2	b.	1	2	1	i i	h	0	
	14	ur.	144					
1	1	1	1	6	9	- 1	5	
Edge	Name		Туре	Read Class	Speed L	init		
a	Ems		Road	A	60			
þ.	High		Street	B	30			
	2		in.					
-	North		Avenue	A	A 40			

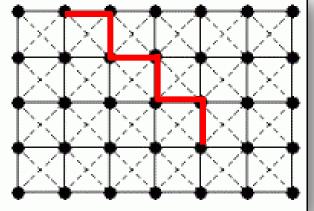




KATEDRA GEOINFORMATIKY Univerzita Palackého v Olomouci

Network modelling in raster GIS

- the grid cells only approximate the exact shapes of the lines in the network
- direction is not explicitly given
- the line and node attributes must be stored as a separate layer for each attribute (a network normally consists of a vast number of layers)
- a grid is in fact a graph representing a network, with 8 possible directions from each node

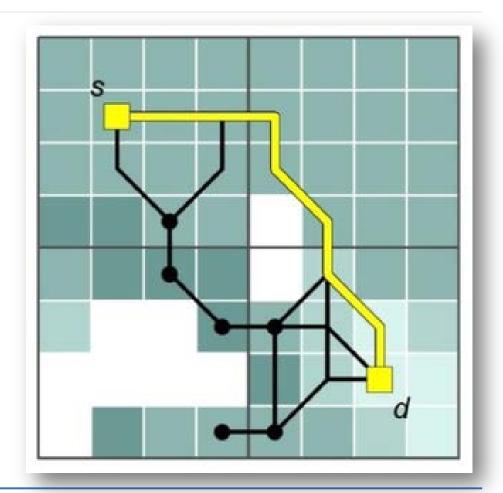




Network modelling in raster GIS

Layers needed:

- network
- cost surface
- origin and destination point



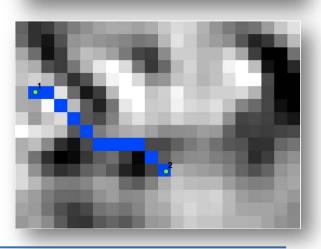


Path finding in raster GIS

Raster GIS software computes the least path as follows:

- the spread function employs the cost surface to calculate the cost of passing from the origin outward towards the destination and assigns the accumulated value to each cell that is passed
- the reverse is done, going from destination to origin
- adding the two accumulated together yields the least-cost path







Conclusions

- vector data model is feature oriented
- raster data model is location oriented
- vector-based network model is more suitable for analysing precisely defined paths, such as roads and rivers or drainage canals (discrete entities that derive mainly from the built environment, and where attributes play a major role in determining the network)
- raster-based network model is more fit, when the problem is concerned with finding a path across terrain (that does not have predefined paths and where the network does not consist of many attribute layers and artificial directional constraints) because that will make the modelling process more complex





DĚKUJI ZA POZORNOST.

